Applications of linear barycentric rational interpolation at equispaced nodes

Jean-Paul Berrut (with Georges Klein and Michael Floater)

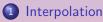
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- Integration of barycentric rational interpolants



Differentiation of barycentric rational interpolants Linear barycentric rational finite differences Integration of barycentric rational interpolants One-dimensional interpolation Barycentric Lagrange interpolation Polynomial to rational interpolation Floater and Hormann interpolation

Introduction and notation

Interpolation



Differentiation of barycentric rational interpolants Linear barycentric rational finite differences Integration of barycentric rational interpolants **One-dimensional interpolation** Barycentric Lagrange interpolation Polynomial to rational interpolation Floater and Hormann interpolation

One-dimensional interpolation problem

Given:

 $a \le x_0 < x_1 < \ldots < x_n \le b, \qquad n+1$ $f(x_0), f(x_1), \ldots, f(x_n), \qquad \text{corres}$

n + 1 distinct nodes and corresponding values.

There exists a unique polynomial of degree $\leq n$ that interpolates the f_i , i.e.

$$p_n[f](x_i) = f_i, \quad i = 0, 1, \dots, n.$$

The Lagrange form of the polynomial interpolant is

$$p_n[f](x) := \sum_{j=0}^n f_j \ell_j(x), \qquad \ell_j(x) := \prod_{k \neq j} \frac{(x - x_k)}{(x_j - x_k)}.$$



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The first barycentric form

Denote the leading factors of the ℓ_j 's by

$$u_j := \prod_{k \neq j} (x_j - x_k)^{-1}, \quad j = 0, 1, \dots, n,$$

the so-called weights, which may be computed in advance. Rewrite the polynomial in its first barycentric form

$$p_n[f](x) = L(x) \sum_{j=0}^n \frac{\nu_j}{x - x_j} f_j,$$

where

$$L(x) := \prod_{k=0}^n (x - x_k).$$



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Advantages

One-dimensional interpolation Barycentric Lagrange interpolation Polynomial to rational interpolation Floater and Hormann interpolation

• evaluation in O(n) operations,

- ease of adding new data (x_{n+1}, f_{n+1}) ,
- numerically best for evaluation.



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The barycentric formula

The constant $f \equiv 1$ is represented exactly by its polynomial interpolant:

$$1 = L(x) \sum_{j=0}^{n} \frac{\nu_j}{x - x_j} = p_n[1](x).$$

Dividing $p_n[f]$ by 1 and cancelling L(x) gives

he barycentric form of the polynomial interpolant





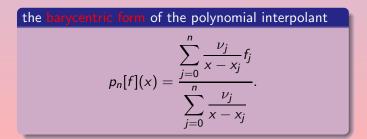
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Advantages

Barycentric Lagrange interpolation Polynomial to rational interpolation Floater and Hormann interpolation

• Interpolation is guaranteed:

$$\lim_{x \to x_k} \frac{\sum_{j=0}^n \frac{\widehat{\nu}_j}{x - x_j} f_j}{\sum_{j=0}^n \frac{\widehat{\nu}_j}{x - x_j}} = f_k.$$

Simplification of the weights:

Cancellation of common factor leads to simplified weights. For equispaced nodes,

$$\nu_j^* = (-1)^j \binom{n}{j}.$$



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Form polynomial to rational interpolation

In the barycentric form of the polynomial interpolant

$$p_n[f](x) = \frac{\sum_{j=0}^n \frac{\nu_j}{x - x_j} f_j}{\sum_{j=0}^n \frac{\nu_j}{x - x_j}},$$

the weights are defined in such a way that

$$L(x)\sum_{j=0}^{n}\frac{\nu_j}{x-x_j}=1.$$

Modification of these weights \rightsquigarrow rational interpolant.



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Lemma

Let $\{x_j\}$, j = 0, 1, ..., n, be n + 1 distinct nodes, $\{f_j\}$ corresponding real numbers and let $\{v_j\}$ be any nonzero real numbers. Then

(a) the rational function

$$T_n[f](x) = rac{{\sum\limits_{j=0}^{n} rac{v_j}{x - x_j} f_j}}{{\sum\limits_{j=0}^{n} rac{v_j}{x - x_j}}},$$

interpolates f_k at x_k : $\lim_{x\to x_k} r_n[f](x) = f_k$;

 (b) conversely, every rational interpolant of the f_j may be written in barycentric form for some weights v_j.

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Floater and Hormann interpolants

Weights suggested in B.(1988):

- (−1)^j;
- $1/2, 1, 1, \ldots, 1, 1, 1/2$ with oscillating sign.

Floater and Hormann in 2007: new choice for the weights ~> family of barycentric rational interpolants.



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Construction presented by Floater and Hormann

- Choose an integer $d \in \{0, 1, \dots, n\}$,
- define $p_j(x)$, the polynomial of degree $\leq d$ interpolating $f_j, f_{j+1}, \ldots, f_{j+d}$ for $j = 0, \ldots, n-d$.

The *d*-th interpolant is given by

$$r_n[f](x) = \frac{\sum_{j=0}^{n-d} \lambda_j(x) p_j(x)}{\sum_{j=0}^{n-d} \lambda_j(x)}, \quad \text{where} \quad \lambda_j(x) = \frac{(-1)^j}{(x-x_j)\dots(x-x_{j+d})}.$$



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Barycentric weights

Write $r_n[f]$ in barycentric form

$$r_n[f](x) = \frac{\sum_{j=0}^n \frac{v_j}{x - x_j} f_j}{\sum_{j=0}^n \frac{v_j}{x - x_j}},$$

with the weights

$$v_j = \sum_{i \in J_j} \prod_{\ell=i, \ \ell \neq j}^{i+d} \frac{1}{x_j - x_\ell}$$



Floater and Hormann interpolation

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Barycentric weights

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For equispaced nodes, the weights v_j oscillate in sign with absolute values

$$\begin{array}{rl} 1,1,\ldots,1,1, & d=0, & (\mathsf{B}.)\\ \frac{1}{2},1,1,\ldots,1,1,\frac{1}{2}, & d=1, & (\mathsf{B}.)\\ \frac{1}{4},\frac{3}{4},1,1,\ldots,1,1,\frac{3}{4},\frac{1}{4}, & d=2, & (\mathsf{Floater-Hormann})\\ \frac{1}{8},\frac{4}{8},\frac{7}{8},1,1,\ldots,1,1,\frac{7}{8},\frac{4}{8},\frac{1}{8}, & d=3. & (\mathsf{Floater-Hormann}) \end{array}$$



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Theorem (Floater-Hormann (2007))

Let $0 \le d \le n$ and $f \in C^{d+2}[a, b]$, $h := \max_{0 \le i \le n-1} (x_{i+1} - x_i)$, then

- the rational function $r_n[f]$ has no poles in \mathbb{R} ,
- if n d is odd, then

$$egin{aligned} \|r_n[f] - f\| &\leq h^{d+1}(b-a) rac{\|f^{(d+2)}\|}{d+2} & ext{if } d \geq 1, \ \|r_n[f] - f\| &\leq h(1+eta)(b-a) rac{\|f''\|}{2} & ext{if } d = 0; \end{aligned}$$

$$\begin{aligned} \|r_n[f] - f\| &\leq h^{d+1} \big((b-a) \frac{\|f^{(d+2)}\|}{d+2} + \frac{\|f^{(d+1)}\|}{d+1} \big) & \text{if } d \geq 1, \\ \|r_n[f] - f\| &\leq h(1+\beta) \big((b-a) \frac{\|f''\|}{2} + \|f'\| \big) & \text{if } d = 0. \\ \beta &:= \max_{1 \leq i \leq n-2} \min \Big\{ \frac{|x_i - x_{i+1}|}{|x_i - x_{i-1}|}, \frac{|x_{i+1} - x_i|}{|x_{i+1} - x_{i+2}|} \Big\} \end{aligned}$$

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Differentiation matrices Convergence rates Example

Differentiation of barycentric rational interpolants



Differentiation matrices Convergence rates Example

Proposition (Schneider-Werner (1986))

Let $r_n[f]$ be a rational function given in its barycentric form with non vanishing weights. Assume that x is not a pole of $r_n[f]$. Then for $k \ge 1$

$$\frac{1}{k!}r_n^{(k)}[f](x) = \frac{\sum_{j=0}^n \frac{v_j}{x - x_j}r_n[f][(x)^k, x_j]}{\sum_{j=0}^n \frac{v_j}{x - x_j}}, \quad x \text{ not a node,}$$
$$\frac{1}{k!}r_n^{(k)}[f](x_i) = -\left(\sum_{\substack{j=0\\j \neq i}}^n v_jr_n[f][(x_i)^k, x_j]\right) / v_i, \quad i = 0, \dots, n.$$



Differentiation matrices Convergence rates Example

Differentiation matrices

Define the matrices $D^{(1)}$ and $D^{(2)}$ (Baltensperger-B.-Noël (1999)):

$$D_{ij}^{(1)} := \begin{cases} \frac{v_j}{v_i} \frac{1}{x_i - x_j}, \\ -\sum_{\substack{n \\ k \neq i}}^n D_{ik}^{(1)}; \\ k \neq i \end{cases}, \quad D_{ij}^{(2)} := \begin{cases} 2D_{ij}^{(1)} \left(D_{ii}^{(1)} - \frac{1}{x_i - x_j} \right), & i \neq j, \\ -\sum_{\substack{k=0 \\ k \neq i}}^n D_{ik}^{(2)}, & i = j. \end{cases}$$

If $f := (f_0, ..., f_n)^T$, then

$$D^{(1)} \cdot \mathbf{f}$$
, respectively $D^{(2)} \cdot \mathbf{f}$,

returns the vector of the first, respectively second, derivative of $r_n[f]$ at the nodes.



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Differentiation matrices Convergence rates Example

Convergence rates for the derivatives

For $x \in [a, b]$, we denote the error

$$e(x) := f(x) - r_n[f](x).$$

Theorem (B.-Floater-Klein)

At the nodes, we have

• if $d \ge 0$ and if $f \in C^{d+2}[a, b]$, then

$$|e'(x_j)| \le Ch^d, \quad j = 0, 1, \dots, n;$$

• if $d \ge 1$ and if $f \in C^{d+3}[a, b]$, then

$$|e''(x_j)| \le Ch^{d-1}, \quad j = 0, 1, \dots, n.$$



Differentiation matrices Convergence rates Example

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Differentiation matrices Convergence rates Example

Theorem (B.-Floater-Klein) (continued)

With the intermediate points, we have

• if $d \ge 1$ and if $f \in C^{d+3}[a, b]$, then

$$\begin{split} \|e'\| &\leq Ch^d & \text{ if } d \geq 2, \\ \|e'\| &\leq C(\beta+1)h & \text{ if } d=1; \end{split}$$

• if
$$d \ge 2$$
 and if $f \in C^{d+4}[a, b]$, then

$$\|e''\| \le C(\beta+1)h^{d-1}$$
 if $d \ge 3$,
 $\|e''\| \le C(\beta^2+\beta+1)h$ if $d=2$.

Mesh ratio

$$\beta := \max\Big\{\max_{1 \le i \le n-1} \frac{|x_i - x_{i+1}|}{|x_i - x_{i-1}|}, \max_{0 \le i \le n-2} \frac{|x_{i+1} - x_i|}{|x_{i+1} - x_{i+2}|}\Big\}.$$



Remarks

Differentiation matrices Convergence rates Example

• In the important cases k = 1, 2 the convergence rate of the k-th derivative is $O(h^{d+1-k})$ as $h \to 0$: In short:

Loss of one order per differentiation.

• Stricter conditions on the differentiability of *f* compared to the interpolant.



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Runge's function

Differentiation matrices Convergence rates Example

Table: Error in the interpolation and the derivatives of the rational interpolant of $1/(1 + x^2)$ in [-5, 5] for d = 3.



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Runge's function

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Interpolation		First derivative		Second derivative		
n	error	order	error	order	error	order
10	6.9e-02		3.9e-01		1.5e+00	
20	2.8e-03	4.6	3.1e-02		2.6e-01	2.5
40	4.3e-06	9.4			1.5e-03	7.4
80	5.1e-08	6.4	1.2e-06		6.1e-05	4.6
160	3.0e-09	4.1	1.0e-07		9.4e-06	2.7
320	1.8e-10	4.0	1.2e-08	3.1	1.2e-06	2.9
640	1.1e-11	4.0	1.5e-09	3.0	3.0e-07	2.0



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80	5.1e-08	6.4	1.2e-06	6.0	6.1e-05	4.6
160	3.0e-09	4.1	1.0e-07	3.6	9.4e-06	2.7
320	1.8e-10	4.0	1.2e-08	3.1	1.2e-06	2.9
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Differentiation matrices Convergence rates Example

Runge's function

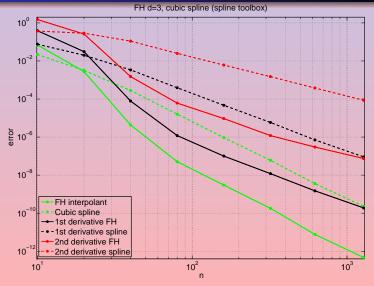
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160	3.0e-09	4.1	1.0e-07	3.6	9.4e-06	2.7
320	1.8e-10	4.0	1.2e-08	3.1	1.2e-06	2.9
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Differentiation matrices Convergence rates Example

Comparison with cubic spline





Higher order derivatives and application to rational finite differences



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Quasi-equispaced nodes

Let us now investigate the convergence rate of the k-th derivative, k = 1, ..., d + 1, of $r_n[f]$ at equispaced or quasi-equispaced nodes. By quasi-equispaced nodes (Elling 2007) we shall mean here points whose minimal spacing h_{\min} satisfies

 $h_{\min} \ge ch$,

where c is a constant.



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Convergence rates for higher order derivatives

Theorem

Suppose n, d, $d \le n$, and k, $k \le d + 1$, are positive integers and $f \in C^{d+1+k}[a, b]$. If the nodes x_j , j = 0, ..., n, are equispaced or quasi-equispaced, then

$$|e^{(k)}(x_j)|\leq Ch^{d+1-k},\quad 0\leq j\leq n,$$

where C only depends on d, k and derivatives of f.



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Rational finite differences (RFD)

Let us introduce **rational finite difference** (RFD) formulas for the approximation, at a node x_i , of the *k*-th derivative of a C^{d+1+k} function,

$$\left. \frac{d^k f}{dx^k} \right|_{x=x_i} \approx \frac{d^k}{dx^k} r_n[f] \right|_{x=x_i} = \sum_{j=0}^n D_{ij}^{(k)} f_j$$

where $D_{ij}^{(k)}$ is the k-th derivative of the *j*-th Lagrange fundamental rational function at the node x_i .



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Rational finite differences (RFD)

Let us introduce **rational finite difference** (RFD) formulas for the approximation, at a node x_i , of the *k*-th derivative of a C^{d+1+k} function,

$$\left. \frac{d^k f}{dx^k} \right|_{x=x_i} \approx \frac{d^k}{dx^k} r_n[f] \right|_{x=x_i} = \sum_{j=0}^n D_{ij}^{(k)} f_j,$$

where $D_{ij}^{(k)}$ is the *k*-th derivative of the *j*-th Lagrange fundamental rational function at the node x_i .



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Rational finite differences (RFD)

In order to establish formulas for the RFD weights $D_{ij}^{(k)}$, we use the differentiation matrix $D^{(1)}$ defined earlier for the first order derivative and the "hybrid formula" (Tee 2006),

$$D_{ij}^{(k)} := \begin{cases} \frac{k}{x_i - x_j} \left(\frac{v_j}{v_i} D_{ii}^{(k-1)} - D_{ij}^{(k-1)} \right), & i \neq j, \\ -\sum_{\substack{\ell = 0 \\ \ell \neq i}}^n D_{i\ell}^{(k)}, & i = j, \end{cases}$$

for higher order derivatives.



Higher order derivatives Linear barycentric rational FD **RFD weights** Examples

Weights for the first centered RFD formulas

Table: Weights for $\mathbf{d} = \mathbf{4}$ for the approximation of the 2-nd and 4-th order derivatives at x = 0 on an equispaced grid.

-4	-3	-2	-1	0	1	2	3	4
2nd de	erivative	(order 3)					
$-\frac{1}{128}$	$\frac{1}{63}$ $\frac{5}{72}$	$-\frac{1}{12}$ $-\frac{5}{28}$ $-\frac{11}{32}$	$\frac{4}{3}$ $\frac{11}{7}$ $\frac{15}{8}$	$-\frac{5}{2}$ $-\frac{355}{126}$ $-\frac{1835}{576}$	4 3 <u>11</u> 7 <u>15</u> 8	$-\frac{1}{12}$ $-\frac{5}{28}$ $-\frac{11}{32}$	$\frac{1}{63}$ $\frac{5}{72}$	$-\frac{1}{128}$
4th de	erivative	(order 1 _,)					
		1	-4	6	-4	1		
<u>1763</u> 12288	$-\frac{109}{441}$ $-\frac{2845}{2304}$	<u>365</u> 147 <u>17017</u> 3072	$-\frac{1133}{147}$ $-\frac{3415}{256}$	<u>4826</u> 441 <u>327787</u> 18432	$-\frac{1133}{147} \\ -\frac{3415}{256}$	365 147 <u>17017</u> 3072	$-\frac{109}{441}$ $-\frac{2845}{2304}$	<u>1763</u> 12288

Berrut



Higher order derivatives Linear barycentric rational FD **RFD weights** Examples

Weights for the first one-sided RFD formulas

Table: Weights for $\mathbf{d} = \mathbf{4}$ for the approximation of the 2-nd and 4-th order derivatives at x = 0 on an equispaced grid.

0	1	2	3	4	5	6	7	8
2nd deri	vative (or	der 3)						
$\begin{array}{r} \frac{35}{12} \\ \frac{15}{4} \\ \frac{319}{90} \\ \frac{379}{105} \\ \frac{42143}{11760} \end{array}$	$-\frac{26}{3} - \frac{77}{6} - \frac{25}{2} - \frac{529}{42} - \frac{1055}{84}$	$ \frac{19}{2} \frac{107}{6} \frac{77}{4} \frac{8129}{420} \frac{3245}{168} 4 1) $	$-\frac{14}{3} \\ -13 \\ -\frac{161}{9} \\ -\frac{809}{42} \\ -\frac{1615}{84}$	$ \begin{array}{r} 11 \\ 12 \\ 61 \\ 12 \\ 11 \\ $	$-\frac{5}{6} \\ -\frac{41}{10} \\ -\frac{1903}{210} \\ -\frac{1727}{140}$	25 36 293 84 429 56	$-\frac{127}{210}$ $-\frac{1775}{588}$	<u>179</u> 336
	ative (or							
1	-4	6	-4	1				
3	-14	26	-24	11	-2			
$\begin{array}{r} \frac{1774}{1125}\\ \underline{9701}\\ 4410\\ \underline{326620243}\\ 172872000 \end{array}$	$-\frac{83}{10} \\ -\frac{3127}{294} \\ -\frac{785833}{82320}$	2827 150 <u>33253</u> 1470 <u>17221193</u> 823200	$-\frac{5383}{225} \\ -\frac{26069}{882} \\ -\frac{6868019}{246960}$	$\begin{array}{r} \frac{451}{25} \\ \frac{2719}{98} \\ \frac{2892553}{102900} \end{array}$	$-\frac{5741}{750} \\ -\frac{27577}{1470} \\ -\frac{16757309}{686000}$	637 450 6901 882 40726213 2469600	$-\frac{2113}{1470} \\ -\frac{3976513}{576240}$	<u>2097749</u> 1646400



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Weights for the first centered RFD formulas

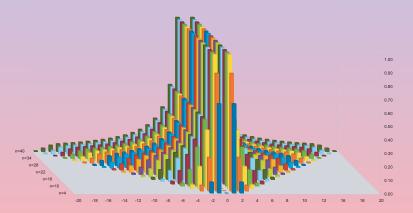


Figure: Absolute values of the weights for $\mathbf{d} = \mathbf{3}$ for the approximation of the first order derivative at x = 0 on an equispaced grid.



Higher order derivatives Linear barycentric rational FD **RFD weights** Examples

Weights for the first one-sided RFD formulas

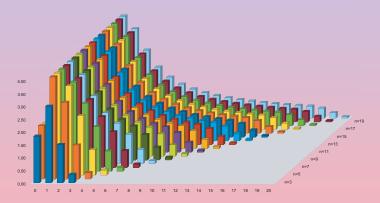


Figure: Absolute values of the weights for d = 3 for the approximation of the first order derivative at x = 0 on an equispaced grid.



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Relative errors in centered FD, resp. RFD for d = 4

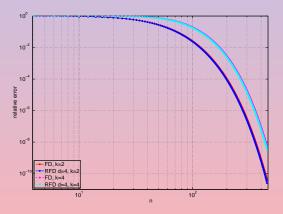


Figure: Relative errors in the approximation at x = 0 of the second and fourth order derivatives of $1/(1+25x^2)$ sampled in [-5,5].



Higher order derivatives Linear barycentric rational FD RFD weights Examples

Errors in one-sided FD, resp. RFD for d = 4

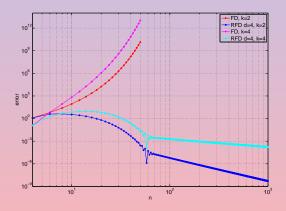


Figure: Errors in the approximation at x = -5 of the second and fourth order derivatives of $1/(1 + x^2)$ sampled in [-5, 5].

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Interpolation	Integration of rational interpolants
Differentiation of barycentric rational interpolants	DRQ
Linear barycentric rational finite differences	IRQ
Integration of barycentric rational interpolants	Example

Integration of barycentric rational interpolants



Integration of rational interpolants DRQ IRQ Example

Quadrature from equispaced samples

Problem: Given a real integrable function f sampled at n + 1 points, approximate

$$I:=\int_a^b f(x)dx$$

by a linear quadrature rule $\sum_{k=0}^{n} w_k f_k$, where f_0, \ldots, f_n are the given data.

Two main situations:

- We can choose the points
 - ---- Gauss quadrature, Clenshaw-Curtis, ...
- f is sampled at n + 1 equispaced points



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Integration of rational interpolants DRQ IRQ Example

Integration of rational interpolants

Every linear interpolation formula trivially leads to a linear quadrature rule.

For a barycentric rational interpolant, we have:

$$I = \int_{a}^{b} f(x) dx \approx \int_{a}^{b} r_{n}[f](x) dx = \int_{a}^{b} \frac{\sum_{k=0}^{n} \frac{v_{k}}{x - x_{k}} f_{k}}{\sum_{j=0}^{n} \frac{v_{j}}{x - x_{j}}} dx$$
$$= \sum_{k=0}^{n} w_{k} f_{k} =: Q_{n},$$

where

$$w_k := \int_a^b \frac{\frac{v_k}{x - x_k}}{\sum_{j=0}^n \frac{v_j}{x - x_j}} dx.$$



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Integration of rational interpolants DRQ IRQ Example

Our suggestions

For true rational interpolants whose denominator degree exceeds 4, there is no straightforward way to establish a linear rational quadrature rule.

We are describing two ideas on how to do this, a direct and an indirect one, avoiding expensive partial fraction decompositions and algebraic methods.



Integration of rational interpolants DRQ IRQ Example

Our suggestions

For true rational interpolants whose denominator degree exceeds 4, there is no straightforward way to establish a linear rational quadrature rule.

We are describing two ideas on how to do this, a **direct** and an **indirect** one, avoiding expensive partial fraction decompositions and algebraic methods.



Integration of rational interpolants DRQ IRQ Example

Direct rational quadrature (DRQ)

Direct rational quadrature rules are based on the numerical stability of the rational interpolant and on well-behaved quadrature rules such as Gauss-Legendre or Clenshaw-Curtis.

Let $w_k^{\mathcal{D}}$, k = 0, ..., n, be some approximations of the weights w_k in Q_n ; then the direct rational quadrature rule reads

$$I = \int_{a}^{b} f(x) dx \approx \sum_{k=0}^{n} w_{k}^{\mathcal{D}} f_{k}$$

instead of Q_n .



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Integration of rational interpolants DRQ IRQ Example

Convergence and degree of precision of DRQ in general

Error in interpolation: $O(h^p)$, error in the quadrature approximating $\int_a^b r_n[f](x)dx$: $O(h^q)$. If $q \ge p$, then

$$\left| \int_{a}^{b} f(x) dx - \sum_{k=0}^{n} w_{k}^{\mathcal{D}} f_{k} \right| \leq \int_{a}^{b} |f(x) - r_{n}[f](x)| dx$$
$$+ \left| \int_{a}^{b} r_{n}[f](x) dx - \sum_{k=0}^{n} w_{k}^{\mathcal{D}} f_{k} \right|$$
$$\leq Ch^{p}.$$

Similar arguments hold for the degree of precision.



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Integration of rational interpolants DRQ IRQ Example

Convergence rates of DRQ in a particular case

Theorem

Suppose n and d, $d \le n/2 - 1$, are nonnegative integers, $f \in C^{d+3}[a, b]$ and $r_n[f]$ belongs to the family of interpolants presented by Floater and Hormann, interpolating f at equispaced nodes. Let the quadrature weights w_k in Q_n be approximated by a quadrature rule converging at least at the rate of $O(h^{d+2})$. Then

$$\Big|\int_a^b f(x)dx - \sum_{k=0}^n w_k^{\mathcal{D}}f_k\Big| \leq Ch^{d+2},$$

where C is a constant depending only on d, on derivatives of f and on the interval length b - a.



Integration of rational interpolants DRQ IRQ Example

Indirect rational quadrature (IRQ)

Indirect quadrature means that we approximate a primitive in the interval [a, b] by a linear rational interpolant. For $x \in [a, b]$, we write the problem

$$r_n[u](x) \approx \int_a^x f(y) dy$$

as an ODE

$$r'_n[u](x) \approx f(x), \quad r_n[u](a) = 0$$

and collocate at the interpolation points.



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Integration of rational interpolants DRQ IRQ Example

Indirect rational quadrature (IRQ)

To this end we make use of the formula for the first derivative of a rational interpolant explained earlier, giving the vector \mathbf{u}' of the first derivative of $r_n[u]$ at the interpolation points

 $\mathbf{u}' = D\mathbf{u},$

where

$$D_{ij} := D_{ij}^{(1)} = \begin{cases} \frac{v_j}{v_i} \frac{1}{x_i - x_j}, & i \neq j, \\ -\sum_{\substack{k=0 \\ k \neq i}}^n D_{ik}^{(1)}, & i = j. \end{cases}$$

Remark: The matrix D is centro-skew symmetric.



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Integration of rational interpolants DRQ IRQ Example

Indirect rational quadrature (IRQ)

Set
$$\mathbf{u} = (u_0, \dots, u_n)^T$$
, $\mathbf{f} = (f_0, \dots, f_n)^T$ and solve the system

$$\sum_{j=1}^n D_{ij}u_j = f_i, \quad i = 1, \dots, n.$$

The approximation u_n of the integral and thus the indirect rational quadrature formula may be given by Cramer's rule

$$u_{n} = \frac{1}{\det\left(\left(D_{ij}\right)_{1 \le i, j \le n}\right)} \sum_{k=1}^{n} \det\left(\begin{array}{ccc} & & & & & \\ & & & & \\ \left(D_{ij}\right)_{1 \le i \le n} & & 1 & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & &$$



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$$=:\sum_{k=1}^{n}w_{k}^{\mathcal{I}}f_{k}.$$

Integration of rational interpolants DRQ IRQ Example

Results for $f(x) = \sin(100x) + 100$

Table: Error in the interpolation and the rational quadrature of f(x) = sin(100x) + 100 for $\mathbf{d} = \mathbf{5}$ at equispaced points in [0, 1] (computing the $w_k^{\mathcal{D}}$ by a Gauss-Legendre quadrature with 125 points).



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Interpolation		DRQ		IRQ		
n	error	order	error	order	error	order
20	2.0e+00		6.8e-03		2.7e-03	
40	1.8e+00	0.2	1.4e-03	2.3		-4.3
80	2.8e-02	6.0		4.0	7.7e-04	6.2
160	6.6e-04	5.4	1.8e-07			
320	9.6e-06	6.1			1.6e-06	
640	1.3e-07	6.3	4.8e-11		3.4e-08	
1280	1.1e-09	6.9	3.0e-13	7.3	7.3e-10	5.6



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20	2.0e+00		6.8e-03		2.7e-03	
40	1.8e+00	0.2	1.4e-03	2.3		-4.3
80	2.8e-02	6.0	9.0e-05	4.0	7.7e-04	6.2
160	6.6e-04	5.4	1.8e-07	9.0		
320	9.6e-06	6.1	5.7e-09	5.0	1.6e-06	
640	1.3e-07	6.3	4.8e-11	6.9	3.4e-08	
1280	1.1e-09	6.9	3.0e-13	7.3	7.3e-10	5.6



Integration of rational interpolants DRQ IRQ Example

Results for $f(x) = \sin(100x) + 100$

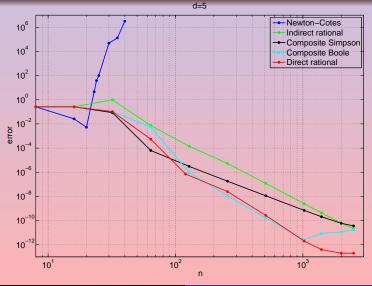
Table: Error in the interpolation and the rational quadrature of f(x) = sin(100x) + 100 for $\mathbf{d} = \mathbf{5}$ at equispaced points in [0, 1] (computing the $w_k^{\mathcal{D}}$ by a Gauss-Legendre quadrature with 125 points).

_	Interpolation		DRQ		IRQ	
n	error	order	error	order	error	order
20	2.0e+00		6.8e-03		2.7e-03	
40	1.8e+00	0.2	1.4e-03	2.3	5.5e-02	-4.3
80	2.8e-02	6.0	9.0e-05	4.0	7.7e-04	6.2
160	6.6e-04	5.4	1.8e-07	9.0	5.7e-05	3.7
320	9.6e-06	6.1	5.7e-09	5.0	1.6e-06	5.2
640	1.3e-07	6.3	4.8e-11	6.9	3.4e-08	5.5
1280	1.1e-09	6.9	3.0e-13	7.3	7.3e-10	5.6



Integration of rational interpolants DRQ IRQ Example

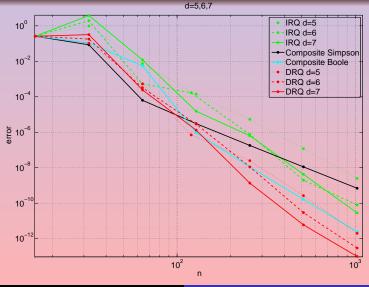
Comparison for f(x) = sin(100x) + 100





Integration of rational interpolants DRQ IRQ Example

Comparison for $f(x) = \sin(100x) + 100$





Interpolation	Integration of rational interpolants
Differentiation of barycentric rational interpolants	DRQ
Linear barycentric rational finite differences	IRQ
Integration of barycentric rational interpolants	Example

Note...

In contrast with DRQ, IRQ yields not only the value u_n approximating the integral, but also approximate values of the primitive $\int_a^x f(y) dy$ at x_1, \ldots, x_{n-1} as u_1, \ldots, u_{n-1} and at all other $x \in [a, b]$ as the interpolant

$$\frac{\sum_{j=0}^{n} \frac{v_j}{x - x_j} u_j}{\sum_{j=0}^{n} \frac{v_j}{x - x_j}} = r_n[u](x) \approx \int_a^x f(y) dy, \quad x \in [a, b].$$

This approximate primitive is infinitely smooth.



Thank you for your attention!

